

A Study on W_6 and W_8 -Curvature Tensors on $(LPK)_n$ -Manifold with a Quarter-Symmetric Metric Connection

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Abstract. The present paper deals with the study of W_6 and W_8 -curvature tensors in an n -dimensional Lorentzian para-Kenmotsu manifold (briefly, $(LPK)_n$ -manifold) with a quarter-symmetric metric connection.

1. INTRODUCTION

In 1971, a class of contact Riemannian manifolds satisfying some special conditions was proposed by Kenmotsu [1], we call it Kenmotsu manifold. After that Kenmotsu manifolds have been studied by many authors, such as Yoldas and Yasar [2]; Jun, De and Pathak [3]; Prasad, Haseeb and Pooja [4] and many others. In 1976, the concept of almost paracontact manifolds was proposed by Sato [5]. An almost paracontact structure on a semi-Riemannian manifold was established by Kaneyuki and Kozai in [6]. They constructed almost paracomplex structure on $M \times R$. According to Kaneyuki et al. [7], the key variation among almost paracontact manifolds is the signature of the metric. In 1995, the authors Sinha and Prasad studied para-Kenmotsu as well as special para-Kenmotsu manifolds and found their significant properties [8]. Afterwards, para-Kenmotsu manifolds drew huge attention of geometers, and significant characteristics of such manifolds have been obtained. Semi-Riemannian geometry, used in the relativity theory, was studied by Neill [9]. About four decades ago, Kaigorodov has explored the curvature structure of the spacetime [10].

Received: Feb. 24, 2025.

2020 *Mathematics Subject Classification.* 53C15, 53C25.

Key words and phrases. W_6 -curvature tensor; W_8 -curvature tensor; Lorentzian para-Kenmotsu manifolds; Riemann curvature tensor; Ricci tensor.

Raychaudhuri et al. [11] extended the concept of general theory of spacetime. Recently, Haseeb and Prasad introduced and studied Lorentzian para-Kenmotsu manifolds of dimension n (briefly, $(LPK)_n$ -manifold) [12, 13].

In 1975, the notion of quarter-symmetric connection in a differentiable manifold was defined and studied by Golab [14]. A quarter-symmetric metric connection has been studied by many geometers in many ways to a different extent as Mandal and De [15], Ahmad et al. [16], Prasad and Haseeb [17] and others. In [18], Pokhariyal have defined W_6 and W_8 -curvature tensors, and it is shown that if the divergence of W_6 -curvature tensor in an electromagnetic field vanishes then it is a purely electric field.

This paper has been organized in the following way: Section 2 contains preliminaries, where some fundamental results are given. In Section 3, curvature tensor of $(LPK)_n$ -manifolds with a quarter-symmetric metric connection is described. In Section 4, we express W_6 and W_8 curvature tensors of $(LPK)_n$ -manifolds with a quarter-symmetric metric connection. In Section 5, non-flatness of W_6 and W_8 -curvature tensors in $(LPK)_n$ -manifold with a quarter-symmetric metric connection are discussed. In Section 6, the relation between W_6 and \bar{W}_8 -curvature tensors is established. In Section 7, we study $(LPK)_n$ manifolds with a quarter-symmetric metric connection satisfying the conditions $\bar{W}_6 \cdot \bar{R}=0$ and $\bar{W}_8 \cdot \bar{R}=0$.

2. PRELIMINARIES

We begin this section with the following definition:

Definition 2.1. A differentiable manifold M is said to be a Lorentzian manifold, if M has a Lorentzian metric g which is a symmetric non-degenerate $(0, 2)$ tensor field of index 1. Since the Lorentzian metric g is of index 1, therefore, Lorentzian manifolds M has not only spacelike vector fields but also lightlike and timelike vector fields.

Definition 2.2. Let M be an n -dimensional Lorentzian metric manifold. If it is endowed with a structure (ϕ, ξ, η, g) , where ϕ is a $(1, 1)$ tensor field, ξ is a vector field, η is a 1-form and g is a Lorentzian metric, satisfying

$$\phi^2 \mathcal{X}_1 = \mathcal{X}_1 + \eta(\mathcal{X}_1)\xi, \quad g(\phi \mathcal{X}_1, \phi \mathcal{X}_2) = g(\mathcal{X}_1, \mathcal{X}_2) + \eta(\mathcal{X}_1)\eta(\mathcal{X}_2), \quad \eta(\xi) = -1, \quad (2.1)$$

$$g(\mathcal{X}_1, \xi) = \eta(\mathcal{X}_1), \quad \phi \xi = 0, \quad \eta(\phi \mathcal{X}_1) = 0, \quad \Phi(\mathcal{X}_1, \mathcal{X}_2) = \Phi(\mathcal{X}_2, \mathcal{X}_1), \quad (2.2)$$

for any vector fields $\mathcal{X}_1, \mathcal{X}_2 \in \chi(M)$: the set of all differentiable vector fields on M , where $\Phi(\mathcal{X}_1, \mathcal{X}_2) = g(\mathcal{X}_1, \phi \mathcal{X}_2)$, then it is called Lorentzian almost paracontact manifold.

Definition 2.3. A Lorentzian almost paracontact manifold M is called $(LPK)_n$ -manifold, if [12]

$$(\nabla_{\mathcal{X}_1} \phi) \mathcal{X}_2 = -g(\phi \mathcal{X}_1, \mathcal{X}_2)\xi - \eta(\mathcal{X}_2)\phi \mathcal{X}_1,$$

where $\mathcal{X}_1, \mathcal{X}_2 \in \chi(M)$.

In an $(LPK)_n$ -manifold, we have [12]

$$\begin{aligned} \nabla_{\mathcal{X}_1}\xi &= -\mathcal{X}_1 - \eta(\mathcal{X}_1)\xi, \\ (\nabla_{\mathcal{X}_1}\eta)\mathcal{X}_2 &= -g(\mathcal{X}_1, \mathcal{X}_2) - \eta(\mathcal{X}_1)\eta(\mathcal{X}_2), \end{aligned}$$

where ∇ denotes the operator of the covariant differentiation with respect to the Lorentzian metric g .

Further, in an $(LPK)_n$ -manifold, the following relations hold [12, 19]:

$$\eta(R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3) = g(\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) - g(\mathcal{X}_1, \mathcal{X}_3)\eta(\mathcal{X}_2), \tag{2.3}$$

$$R(\xi, \mathcal{X}_1)\mathcal{X}_2 = g(\mathcal{X}_1, \mathcal{X}_2)\xi - \eta(\mathcal{X}_2)\mathcal{X}_1, \tag{2.4}$$

$$R(\mathcal{X}_1, \mathcal{X}_2)\xi = \eta(\mathcal{X}_2)\mathcal{X}_1 - \eta(\mathcal{X}_1)\mathcal{X}_2, \tag{2.5}$$

$$R(\xi, \mathcal{X}_1)\xi = \mathcal{X}_1 + \eta(\mathcal{X}_1)\xi, \tag{2.6}$$

$$S(\mathcal{X}_1, \xi) = (n - 1)\eta(\mathcal{X}_1), \quad S(\xi, \xi) = -(n - 1), \tag{2.7}$$

$$Q\xi = (n - 1)\xi, \tag{2.8}$$

$$S(\phi\mathcal{X}_1, \phi\mathcal{X}_2) = S(\mathcal{X}_1, \mathcal{X}_2) + (n - 1)\eta(\mathcal{X}_1)\eta(\mathcal{X}_2), \tag{2.9}$$

for any $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$, here R, S and Q are the curvature tensor, the Ricci tensor, and the Ricci operator of $M(\phi, \xi, \eta, g)$, respectively.

Definition 2.4. A linear connection $\bar{\nabla}$ defined on (M, g) is said to be a quarter-symmetric connection [14], if its torsion tensor T

$$T(\mathcal{X}_1, \mathcal{X}_2) = \bar{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 - \bar{\nabla}_{\mathcal{X}_2}\mathcal{X}_1 - [\mathcal{X}_1, \mathcal{X}_2]$$

satisfies

$$T(\mathcal{X}_1, \mathcal{X}_2) = \eta(\mathcal{X}_2)\phi\mathcal{X}_1 - \eta(\mathcal{X}_1)\phi\mathcal{X}_2,$$

where η is a 1-form and ϕ is a $(1, 1)$ -tensor field. Moreover, if a quarter-symmetric connection $\bar{\nabla}$ satisfies the condition

$$(\bar{\nabla}_{\mathcal{X}_1}g)(\mathcal{X}_2, \mathcal{X}_3) = 0,$$

where $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$, then $\bar{\nabla}$ is said to be a quarter-symmetric metric connection.

A relation between a quarter-symmetric metric connection $\bar{\nabla}$ and the Levi-Civita connection ∇ in an $(LPK)_n$ -manifold M is given by

$$\bar{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 = \nabla_{\mathcal{X}_1}\mathcal{X}_2 + \eta(\mathcal{X}_2)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_2)\xi. \tag{2.10}$$

3. CURVATURE TENSOR OF $(LPK)_n$ -MANIFOLD WITH A QUARTER-SYMMETRIC METRIC CONNECTION

The curvature tensor \bar{R} with a quarter-symmetric metric connection $\bar{\nabla}$ is defined by

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \bar{\nabla}_{\mathcal{X}_1}\bar{\nabla}_{\mathcal{X}_2}\mathcal{X}_3 - \bar{\nabla}_{\mathcal{X}_2}\bar{\nabla}_{\mathcal{X}_1}\mathcal{X}_3 - \bar{\nabla}_{[\mathcal{X}_1, \mathcal{X}_2]}\mathcal{X}_3. \quad (3.1)$$

Using the relation (2.10) in (3.1), we have

$$\begin{aligned} \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + g(\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2 + g(\phi\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 \\ &\quad - g(\phi\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 + g(\phi\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2, \end{aligned} \quad (3.2)$$

where

$$R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \nabla_{\mathcal{X}_1}\nabla_{\mathcal{X}_2}\mathcal{X}_3 - \nabla_{\mathcal{X}_2}\nabla_{\mathcal{X}_1}\mathcal{X}_3 - \nabla_{[\mathcal{X}_1, \mathcal{X}_2]}\mathcal{X}_3,$$

is the Riemannian curvature tensor of the connection ∇ . Taking the inner product of (3.2) with \mathcal{U}_3 , we have

$$\begin{aligned} \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_3) &= R(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_3) + g(\mathcal{X}_2, \mathcal{X}_3)g(\phi\mathcal{X}_1, \mathcal{U}_3) - g(\mathcal{X}_1, \mathcal{X}_3)g(\phi\mathcal{X}_2, \mathcal{U}_3) \\ &\quad + g(\phi\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_3) - g(\phi\mathcal{X}_1, \mathcal{X}_3)g(\mathcal{X}_2, \mathcal{U}_3) + g(\phi\mathcal{X}_2, \mathcal{X}_3)g(\phi\mathcal{X}_1, \mathcal{U}_3) \\ &\quad - g(\phi\mathcal{X}_1, \mathcal{X}_3)g(\phi\mathcal{X}_2, \mathcal{U}_3), \end{aligned} \quad (3.3)$$

where $\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_3) = g(\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3, \mathcal{U}_3)$, and $R(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_3) = g(R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3, \mathcal{U}_3)$.

Contracting (3.3) over \mathcal{X}_1 and \mathcal{U}_3 , we obtain

$$\bar{S}(\mathcal{X}_2, \mathcal{X}_3) = S(\mathcal{X}_2, \mathcal{X}_3) + (n + \psi - 2)g(\phi\mathcal{X}_2, \mathcal{X}_3) + (\psi - 1)g(\mathcal{X}_2, \mathcal{X}_3) - \eta(\mathcal{X}_2)\eta(\mathcal{X}_3), \quad (3.4)$$

where, S and \bar{S} are the Ricci tensors of the connections ∇ and $\bar{\nabla}$, respectively on M , and $\psi = \text{trace } \phi$.

Replacing $\mathcal{X}_3 = \xi$ in (3.4), and using (2.2) and (2.7), we have

$$\bar{S}(\mathcal{X}_2, \xi) = (n + \psi - 1)\eta(\mathcal{X}_2). \quad (3.5)$$

From (3.4), we have

$$\bar{Q}\mathcal{X}_2 = Q\mathcal{X}_2 + (n + \psi - 2)\phi\mathcal{X}_2 + (\psi - 1)\mathcal{X}_2 - \eta(\mathcal{X}_2)\xi, \quad (3.6)$$

where Q and \bar{Q} are the Ricci operators of the connections ∇ and $\bar{\nabla}$, respectively on M .

Replacing $\mathcal{X}_3 = \xi$ in (3.6), we have

$$\bar{Q}\xi = (n + \psi - 1)\xi. \quad (3.7)$$

Contracting (3.4) over \mathcal{X}_2 and \mathcal{X}_3 , we find

$$\bar{r} = r + (2\psi - 1)(n - 1) + \psi^2, \quad (3.8)$$

where r and \bar{r} are the scalar curvatures of the connections ∇ and $\bar{\nabla}$, respectively on M .

From (3.2), we deduce

$$\bar{R}(\xi, \mathcal{X}_2)\mathcal{X}_3 = g(\mathcal{X}_2, \mathcal{X}_3)\xi - \eta(\mathcal{X}_3)\mathcal{X}_2 - \eta(\mathcal{X}_3)\phi\mathcal{X}_2 + g(\phi\mathcal{X}_2, \mathcal{X}_3)\xi, \quad (3.9)$$

$$\bar{R}(\mathcal{X}_1, \xi)\mathcal{X}_3 = \eta(\mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\xi + \eta(\mathcal{X}_3)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\xi, \quad (3.10)$$

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\xi = \eta(\mathcal{X}_2)\mathcal{X}_1 - \eta(\mathcal{X}_1)\mathcal{X}_2 + \eta(\mathcal{X}_2)\phi\mathcal{X}_1 - \eta(\mathcal{X}_1)\phi\mathcal{X}_2, \quad (3.11)$$

for any $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$.

4. EXPRESSION OF W_6 AND W_8 -CURVATURE TENSORS ON $(LPK)_n$ -MANIFOLDS WITH A QUARTER-SYMMETRIC METRIC CONNECTION

The W_6 -curvature tensor field in a Riemannian manifold is defined as [20,21]

$$W_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}[g(\mathcal{X}_1, \mathcal{X}_2)Q\mathcal{X}_3 - S(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1], \quad (4.1)$$

for any $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$.

Analogous to (4.1), the W_6 -curvature tensor in an $(LPK)_n$ -manifold with a quarter-symmetric metric connection $\bar{\nabla}$ is defined by

$$\bar{W}_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}[g(\mathcal{X}_1, \mathcal{X}_2)\bar{Q}\mathcal{X}_3 - \bar{S}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1]. \quad (4.2)$$

By using (3.2) and (3.6) in (4.2), we have

$$\begin{aligned} \bar{W}_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}[g(\mathcal{X}_1, \mathcal{X}_2)Q\mathcal{X}_3 - S(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1] \\ &+ \frac{n+\psi-2}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\phi\mathcal{X}_3 + g(\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2 \\ &+ \frac{\psi-1}{n-1}[g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - g(\phi\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1] - g(\phi\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &+ g(\phi\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2 \\ &+ \frac{1}{n-1}[\eta(\mathcal{X}_2)\eta(\mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{X}_3)\xi]. \end{aligned} \quad (4.3)$$

Taking $\mathcal{X}_1 = \xi$, $\mathcal{X}_2 = \xi$ and $\mathcal{X}_3 = \xi$ in (4.3), we respectively have

$$\begin{aligned} \bar{W}_6(\xi, \mathcal{X}_2)\mathcal{X}_3 &= \frac{n-\psi}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\xi - \frac{\psi-1}{n-1}g(\phi\mathcal{X}_2, \mathcal{X}_3)\xi + \frac{\psi-1}{n-1}\eta(\mathcal{X}_2)\mathcal{X}_3 - \eta(\mathcal{X}_3)\mathcal{X}_2 \\ &+ \frac{n+\psi-2}{n-1}\eta(\mathcal{X}_2)\phi\mathcal{X}_3 - \eta(\mathcal{X}_3)\phi\mathcal{X}_2 + \frac{1}{n-1}[\eta(\mathcal{X}_2)Q\mathcal{X}_3 - S(\mathcal{X}_2, \mathcal{X}_3)\xi], \end{aligned} \quad (4.4)$$

$$\begin{aligned} \bar{W}_6(\mathcal{X}_1, \xi)\mathcal{X}_3 &= \frac{\psi-1}{n-1}\eta(\mathcal{X}_1)\mathcal{X}_3 - \frac{\psi}{n-1}\eta(\mathcal{X}_3)\mathcal{X}_1 + \frac{n+\psi-2}{n-1}\eta(\mathcal{X}_1)\phi\mathcal{X}_3 + \eta(\mathcal{X}_3)\phi\mathcal{X}_1 \\ &- g(\mathcal{X}_1, \mathcal{X}_3)\xi - g(\phi\mathcal{X}_1, \mathcal{X}_3)\xi - \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_3)\xi + \frac{1}{n-1}\eta(\mathcal{X}_1)Q\mathcal{X}_3, \end{aligned} \quad (4.5)$$

$$\begin{aligned} \bar{W}_6(\mathcal{X}_1, \mathcal{X}_2)\xi &= -\eta(\mathcal{X}_1)\mathcal{X}_2 - \frac{\psi}{n-1}\eta(\mathcal{X}_2)\mathcal{X}_1 + \eta(\mathcal{X}_2)\phi\mathcal{X}_1 \\ &- \eta(\mathcal{X}_1)\phi\mathcal{X}_2 + \frac{n+\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\xi. \end{aligned} \quad (4.6)$$

Taking the inner product of (4.3) with ξ , we get

$$\begin{aligned} \eta(\bar{W}_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3) &= \frac{n+\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{X}_3) + \frac{n-\psi}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) \\ &- g(\mathcal{X}_1, \mathcal{X}_3)\eta(\mathcal{X}_2) - \frac{\psi-1}{n-1}g(\phi\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) - g(\phi\mathcal{X}_1, \mathcal{X}_3)\eta(\mathcal{X}_2) \\ &+ \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\eta(\mathcal{X}_3) - \frac{1}{n-1}S(\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1). \end{aligned} \quad (4.7)$$

Now, the W_8 -curvature tensor in Kenmotsu manifolds with the Levi-Civita connection ∇ is given by

$$W_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{n-1}[S(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3]. \quad (4.8)$$

Analogous to (4.8), the W_8 -curvature tensor in $(LPK)_n$ -manifold with a quarter-symmetric metric connection $\bar{\nabla}$ is defined by

$$\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{n-1}[\bar{S}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3]. \quad (4.9)$$

By using (3.2) and (3.4) in (4.9), we have

$$\begin{aligned} &\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 \\ &= R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{n-1}[S(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3] \\ &- \frac{\psi-1}{n-1}[g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3] + g(\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2 \\ &+ \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{\psi-1}{n-1}g(\phi\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &+ g(\phi\mathcal{X}_2, \mathcal{X}_3)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\phi\mathcal{X}_2 + \frac{1}{n-1}[\eta(\mathcal{X}_2)\eta(\mathcal{X}_3)\mathcal{X}_1 - \eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\mathcal{X}_3]. \end{aligned} \quad (4.10)$$

Taking $\mathcal{X}_1 = \xi$, $\mathcal{X}_2 = \xi$ and $\mathcal{X}_3 = \xi$ in (4.10), we respectively have

$$\begin{aligned} \bar{W}_8(\xi, \mathcal{X}_2)\mathcal{X}_3 &= \frac{n-\psi}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\xi - \eta(\mathcal{X}_3)\mathcal{X}_2 + \frac{n+\psi-1}{n-1}\eta(\mathcal{X}_2)\mathcal{X}_3 - \eta(\mathcal{X}_3)\phi\mathcal{X}_2 \\ &- \frac{\psi-1}{n-1}g(\phi\mathcal{X}_2, \mathcal{X}_3)\xi + \frac{1}{n-1}\eta(\mathcal{X}_2)\eta(\mathcal{X}_3)\xi - \frac{1}{n-1}S(\mathcal{X}_2, \mathcal{X}_3)\xi. \end{aligned} \quad (4.11)$$

$$\begin{aligned} \bar{W}_8(\mathcal{X}_1, \xi)\mathcal{X}_3 &= \frac{n+\psi-1}{n-1}\eta(\mathcal{X}_1)\mathcal{X}_3 - \frac{\psi}{n-1}\eta(\mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\xi \\ &+ \eta(\mathcal{X}_3)\phi\mathcal{X}_1 - g(\phi\mathcal{X}_1, \mathcal{X}_3)\xi. \end{aligned} \quad (4.12)$$

$$\begin{aligned} \bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\xi &= \frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\xi + \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\xi \\ &- \eta(\mathcal{X}_1)\mathcal{X}_2 - \frac{\psi}{n-1}\eta(\mathcal{X}_2)\mathcal{X}_1 + \eta(\mathcal{X}_2)\phi\mathcal{X}_1 - \eta(\mathcal{X}_1)\phi\mathcal{X}_2 \\ &- \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\xi + \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\xi. \end{aligned} \quad (4.13)$$

Taking the inner product of equation (4.10) with ξ , we have

$$\begin{aligned} & \eta(\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3) \\ = & \frac{\psi - 1}{n - 1}g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{X}_3) + \frac{n - \psi}{n - 1}g(\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) \\ - & g(\mathcal{X}_1, \mathcal{X}_3)\eta(\mathcal{X}_2) + \frac{n + \psi - 2}{n - 1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{X}_3) - \frac{\psi - 1}{n - 1}g(\phi\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) \quad (4.14) \\ - & g(\phi\mathcal{X}_1, \mathcal{X}_3)\eta(\mathcal{X}_2) - \frac{1}{n - 1}[S(\mathcal{X}_2, \mathcal{X}_3)\eta(\mathcal{X}_1) - S(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{X}_3)]. \end{aligned}$$

5. NON-FLATNESS OF W_6 AND W_8 -CURVATURE TENSOR IN $(LPK)_n$ -MANIFOLDS WITH A QUARTER-SYMMETRIC METRIC CONNECTION

First, we consider non-flatness of W_6 -curvature tensor in $(LPK)_n$ -manifolds with a quarter-symmetric metric connection. We prove our fact by contradiction, i.e., we assume that an $(LPK)_n$ -manifold with a quarter-symmetric metric connection is W_6 -flat, i.e.,

$$\bar{W}_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = 0, \tag{5.1}$$

for any $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$.

Taking the inner product of (4.2) with \mathcal{U}_2 , we have

$$\begin{aligned} & \bar{W}_6(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) \\ = & \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) + \frac{1}{n - 1}[g(\mathcal{X}_1, \mathcal{X}_2)g(\bar{Q}\mathcal{X}_3, \mathcal{U}_2) - \bar{S}(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2)]. \quad (5.2) \end{aligned}$$

By using equation (5.1), (5.2) gives

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = \frac{1}{n - 1}[\bar{S}(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2) - g(\mathcal{X}_1, \mathcal{X}_2)g(\bar{Q}\mathcal{X}_3, \mathcal{U}_2)].$$

Taking $\mathcal{X}_3 = \xi$ in the above equation, we have

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = \frac{1}{n - 1}[\bar{S}(\mathcal{X}_2, \xi)g(\mathcal{X}_1, \mathcal{U}_2) - g(\mathcal{X}_1, \mathcal{X}_2)g(\bar{Q}\xi, \mathcal{U}_2)]. \tag{5.3}$$

Using equations (3.5) and (3.7) in (5.3), we find

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = \frac{n + \psi - 1}{n - 1}[g(\mathcal{X}_1, \mathcal{U}_2)\eta(\mathcal{X}_2) - g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2)] \neq 0. \tag{5.4}$$

Hence, the above relation leads to the following theorem:

Theorem 5.1. *In an $(LPK)_n$ -manifold with a quarter-symmetric metric connection, \bar{W}_6 -curvature tensor is not flat.*

Next, we consider non-flatness of W_8 -curvature tensor in $(LPK)_n$ -manifolds with a quarter-symmetric metric connection. We assume that an $(LPK)_n$ -manifold with a quarter-symmetric metric connection is W_8 -flat, i.e.,

$$\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = 0, \tag{5.5}$$

for all $\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3 \in \chi(M)$.

By taking the inner product of (4.9) with \mathcal{U}_2 , we have

$$\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) - \frac{1}{n-1} [\bar{S}(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2) - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)g(\mathcal{X}_3, \mathcal{U}_2)]. \quad (5.6)$$

By using (5.5), (5.6) gives

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = \frac{1}{n-1} [\bar{S}(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2) - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)g(\mathcal{X}_3, \mathcal{U}_2)]. \quad (5.7)$$

Taking $\mathcal{X}_3 = \xi$ in (5.7), we have

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = \frac{1}{n-1} [\bar{S}(\mathcal{X}_2, \xi)g(\mathcal{X}_1, \mathcal{U}_2) - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)g(\xi, \mathcal{U}_2)].$$

In view of (3.4) and (3.5), the last equation turns to

$$\begin{aligned} \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) &= \frac{1}{n-1} [(n+\psi-1)\eta(\mathcal{X}_2)g(\mathcal{X}_1, \mathcal{U}_2) - (\psi-1)g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) \\ &\quad - S(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) - (n+\psi-2)g(\phi\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) + \eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\eta(\mathcal{U}_2)] \neq 0. \end{aligned} \quad (5.8)$$

Hence, the above relation leads to the following theorem:

Theorem 5.2. *In an $(LPK)_n$ -manifold with a quarter-symmetric metric connection, \bar{W}_8 -curvature tensor is not flat.*

6. RELATIONSHIP BETWEEN W_6 AND \bar{W}_8 -CURVATURE TENSORS IN $(LPK)_n$ -MANIFOLDS

Taking the inner product of (4.9) with \mathcal{U}_2 , we have

$$\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) - \frac{1}{n-1} [\bar{S}(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2) - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)g(\mathcal{X}_3, \mathcal{U}_2)], \quad (6.1)$$

where $\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = g(\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3, \mathcal{U}_2)$.

Putting $\mathcal{X}_3 = \xi$ in (6.1), we have

$$\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) - \frac{1}{n-1} [\bar{S}(\mathcal{X}_2, \xi)g(\mathcal{X}_1, \mathcal{U}_2) - \bar{S}(\mathcal{X}_1, \mathcal{X}_2)g(\xi, \mathcal{U}_2)]. \quad (6.2)$$

From (3.3), we also have

$$\begin{aligned} \bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) &= R(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) + g(\mathcal{X}_2, \xi)g(\phi\mathcal{X}_1, \mathcal{U}_2) - g(\mathcal{X}_1, \xi)g(\phi\mathcal{X}_2, \mathcal{U}_2) \\ &\quad + g(\phi\mathcal{X}_2, \xi)g(\mathcal{X}_1, \mathcal{U}_2) - g(\phi\mathcal{X}_1, \xi)g(\mathcal{X}_2, \mathcal{U}_2) \\ &\quad + g(\phi\mathcal{X}_2, \xi)g(\phi\mathcal{X}_1, \mathcal{U}_2) - g(\phi\mathcal{X}_2, \mathcal{U}_2). \end{aligned} \quad (6.3)$$

By using (2.2), (6.3) reduces to

$$\bar{R}(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = R(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) + \eta(\mathcal{X}_2)g(\phi\mathcal{X}_1, \mathcal{U}_2) - \eta(\mathcal{X}_1)g(\phi\mathcal{X}_2, \mathcal{U}_2). \quad (6.4)$$

Now, using (2.2), (3.5) and (6.4) in (6.2), we have

$$\begin{aligned}\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) &= R(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) + \frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) - \frac{n+\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{U}_2)\eta(\mathcal{X}_2) \\ &- g(\phi\mathcal{X}_2, \mathcal{U}_2)\eta(\mathcal{X}_1) + g(\phi\mathcal{X}_1, \mathcal{U}_2)\eta(\mathcal{X}_2) + \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) \\ &- \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\eta(\mathcal{U}_2) + \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2).\end{aligned}$$

Interchanging \mathcal{U}_2 and ξ in the foregoing equation, we have

$$\begin{aligned}\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2, \mathcal{U}_2, \xi) &= R(\mathcal{X}_1, \mathcal{X}_2, \mathcal{U}_2, \xi) + \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\eta(\mathcal{U}_2) - \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) \\ &- \frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) + \frac{n+\psi-1}{n-1}g(\mathcal{X}_2, \mathcal{U}_2)\eta(\mathcal{X}_1) - \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2).\end{aligned}\quad (6.5)$$

Equation (6.5) can be written as

$$\begin{aligned}\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 &= R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 + \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\mathcal{U}_2 - \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 \\ &- \frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 + \frac{n+\psi-1}{n-1}g(\mathcal{X}_2, \mathcal{U}_2)\mathcal{X}_1 - \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2.\end{aligned}\quad (6.6)$$

Replacing \mathcal{U}_2 by \mathcal{X}_3 in (6.6), we have

$$\begin{aligned}\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\mathcal{X}_3 - \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 \\ &- \frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{n+\psi-1}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3.\end{aligned}\quad (6.7)$$

Using equation (2.3) in (6.7) and simplifying, we get

$$\begin{aligned}\bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= -\frac{\psi-1}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{2n+\psi-2}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &- \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\mathcal{X}_3 - \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3.\end{aligned}\quad (6.8)$$

Taking the inner product of (4.1) with \mathcal{U}_2 , we have

$$W_6(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) = R(\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3, \mathcal{U}_2) + \frac{1}{n-1}[g(\mathcal{X}_1, \mathcal{X}_2)S(\mathcal{X}_3, \mathcal{U}_2) - S(\mathcal{X}_2, \mathcal{X}_3)g(\mathcal{X}_1, \mathcal{U}_2)],$$

which by putting $\mathcal{X}_3 = \xi$ turns to

$$W_6(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) = R(\mathcal{X}_1, \mathcal{X}_2, \xi, \mathcal{U}_2) + [g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) - g(\mathcal{X}_1, \mathcal{U}_2)\eta(\mathcal{X}_2)].\quad (6.9)$$

Interchanging \mathcal{U}_2 and ξ in the above equation, we have

$$-W_6(\mathcal{X}_1, \mathcal{X}_2, \mathcal{U}_2, \xi) = -R(\mathcal{X}_1, \mathcal{X}_2, \mathcal{U}_2, \xi) + [g(\mathcal{X}_1, \mathcal{X}_2)\eta(\mathcal{U}_2) - g(\mathcal{X}_2, \mathcal{U}_2)\eta(\mathcal{X}_1)],$$

from which we write

$$W_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 = R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 - [g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_2 - g(\mathcal{X}_2, \mathcal{U}_2)\mathcal{X}_1].\quad (6.10)$$

Replacing $\mathcal{U}_2 = \mathcal{X}_3$ in (6.10), we have

$$W_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = R(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - [g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1]. \quad (6.11)$$

Simplifying above, we have

$$W_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = -g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + 2g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - g(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2. \quad (6.12)$$

Now, from (6.8) and (6.12), we get

$$\begin{aligned} \bar{W}_8(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= W_6(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{n-\psi}{n-1}g(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{\psi}{n-1}g(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 \\ &- \frac{n+\psi-2}{n-1}g(\phi\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \frac{1}{n-1}\eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\mathcal{X}_3 - \frac{1}{n-1}S(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3. \end{aligned} \quad (6.13)$$

Thus, we conclude:

Theorem 6.1. *A W_8 -curvature tensor with a quarter-symmetric metric connection is related to the W_6 -curvature tensor with the Levi-Civita connection in $(LPK)_n$ -manifolds by (6.13).*

7. $(LPK)_n$ -MANIFOLDS SATISFYING $\bar{W}_6 \cdot \bar{R} = 0$ AND $\bar{W}_8 \cdot \bar{R} = 0$

In this section, first we study an $(LPK)_n$ -manifold satisfying $\bar{W}_6(\xi, \mathcal{U}_1) \cdot \bar{R} = 0$. Thus, we have

$$\begin{aligned} \bar{W}_6(\xi, \mathcal{U}_1)\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \bar{R}(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 \\ - \bar{R}(\mathcal{X}_1, \bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_2)\mathcal{X}_3 - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_3 = 0. \end{aligned} \quad (7.1)$$

Replacing \mathcal{X}_3 by ξ in (7.1), we have

$$\begin{aligned} \bar{W}_6(\xi, \mathcal{U}_1)\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\xi - \bar{R}(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_1, \mathcal{X}_2)\xi \\ - \bar{R}(\mathcal{X}_1, \bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_2)\xi - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\bar{W}_6(\xi, \mathcal{U}_1)\xi = 0. \end{aligned} \quad (7.2)$$

Using (3.11) in (7.2), we have

$$\begin{aligned} \eta(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_1)\mathcal{X}_2 - \eta(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_2)\mathcal{X}_1 + \eta(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_1)\phi\mathcal{X}_2 \\ - \eta(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_2)\phi\mathcal{X}_1 + \eta(\mathcal{X}_2)\bar{W}_6(\xi, \mathcal{U}_1)\phi\mathcal{X}_1 - \eta(\mathcal{X}_1)\bar{W}_6(\xi, \mathcal{U}_1)\phi\mathcal{X}_2 \\ + \eta(\mathcal{X}_1)\phi(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_2) - \eta(\mathcal{X}_2)\phi(\bar{W}_6(\xi, \mathcal{U}_1)\mathcal{X}_1) - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)(\mathcal{U}_1 + \phi\mathcal{U}_1 + \eta(\mathcal{U}_1)\xi) = 0. \end{aligned} \quad (7.3)$$

By using (4.4) in (7.3), we lead to

$$\begin{aligned} \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 - \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 + \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 \\ - \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 + \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_2)\eta(\mathcal{X}_1)\xi - \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_1)\eta(\mathcal{X}_2)\xi \\ + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 \\ - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 + \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 - \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 \\ + \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 - \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 + \frac{\psi-1}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\eta(\mathcal{X}_1)\xi \end{aligned} \quad (7.4)$$

$$\begin{aligned}
 &-\frac{\psi-1}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\eta(\mathcal{X}_2)\xi + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_1)\eta(\mathcal{X}_2)\xi - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_2)\eta(\mathcal{X}_1)\xi \\
 &+ \frac{n+\psi-2}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\mathcal{X}_2 - \frac{n+\psi-2}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_2)\mathcal{X}_1 + \frac{n+\psi-2}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\phi\mathcal{X}_2 \\
 &-\frac{n+\psi-2}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_2)\phi\mathcal{X}_1 - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_1 - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\phi\mathcal{U}_1 = 0.
 \end{aligned}$$

Substituting $\mathcal{X}_2 = \xi$, and using (3.10) in (7.4), we arrive at

$$\begin{aligned}
 &\frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\xi + \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_1)\xi + \frac{n+2\psi-3}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\xi \\
 &+ \frac{n+\psi-2}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\xi + \frac{\psi-1}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_1)\xi + \frac{2(n+\psi-2)}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\xi = 0.
 \end{aligned} \tag{7.5}$$

Taking the inner product of (7.5) with ξ , we have

$$\begin{aligned}
 S(\mathcal{U}_1, \mathcal{X}_1) + S(\mathcal{U}_1, \phi\mathcal{X}_1) &= -(n+2\psi-3)g(\mathcal{U}_1, \mathcal{X}_1) - (\psi-1)g(\mathcal{U}_1, \phi\mathcal{X}_1) \\
 &\quad - (n+\psi-2)g(\phi\mathcal{U}_1, \mathcal{X}_1) - 2(n+\psi-2)\eta(\mathcal{U}_1)\eta(\mathcal{X}_1).
 \end{aligned} \tag{7.6}$$

Contracting above expression over \mathcal{U}_1 and \mathcal{X}_1 , we obtain

$$r = -[n^2 + (5\psi-1)n - (\psi+4)] - tr\phi Q. \tag{7.7}$$

The above relation leads to the following theorem:

Theorem 7.1. *The scalar curvature of an $(LPK)_n$ -manifold satisfying $\bar{W}_6 \cdot \bar{R} = 0$ is given by (7.7).*

Next, we study an $(LPK)_n$ -manifold satisfying $\bar{W}_8(\xi, \mathcal{U}_1) \cdot \bar{R} = 0$. Thus, we have

$$\begin{aligned}
 &\bar{W}_8(\xi, \mathcal{U}_1)\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \bar{R}(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 \\
 &-\bar{R}(\mathcal{X}_1, \bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_2)\mathcal{X}_3 - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_3 = 0.
 \end{aligned} \tag{7.8}$$

Replacing \mathcal{X}_3 by ξ in (7.8), we have

$$\begin{aligned}
 &\bar{W}_8(\xi, \mathcal{U}_1)\bar{R}(\mathcal{X}_1, \mathcal{X}_2)\xi - \bar{R}(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_1, \mathcal{X}_2)\xi \\
 &-\bar{R}(\mathcal{X}_1, \bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_2)\xi - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\bar{W}_8(\xi, \mathcal{U}_1)\xi = 0.
 \end{aligned} \tag{7.9}$$

Using (3.11) in (7.9), we have

$$\begin{aligned}
 &\eta(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_1)\mathcal{X}_2 - \eta(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_2)\mathcal{X}_1 + \eta(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_1)\phi\mathcal{X}_2 \\
 &-\eta(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_2)\phi\mathcal{X}_1 + \eta(\mathcal{X}_2)\bar{W}_8(\xi, \mathcal{U}_1)\phi\mathcal{X}_1 - \eta(\mathcal{X}_1)\bar{W}_8(\xi, \mathcal{U}_1)\phi\mathcal{X}_2 \\
 &+ \eta(\mathcal{X}_1)\phi(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_2) - \eta(\mathcal{X}_2)\phi(\bar{W}_8(\xi, \mathcal{U}_1)\mathcal{X}_1) - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)(\mathcal{U}_1 \\
 &+ \phi\mathcal{U}_1 + \frac{n}{n-1}\eta(\mathcal{U}_1)\xi) = 0.
 \end{aligned} \tag{7.10}$$

By using (4.11), (7.10) becomes

$$\begin{aligned}
& \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 - \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 + \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 \\
& - \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 + \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_2)\eta(\mathcal{X}_1)\xi - \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_1)\eta(\mathcal{X}_2)\xi \\
& + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 \\
& - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 + \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\mathcal{X}_2 - \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_2)\mathcal{X}_1 \\
& + \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\phi\mathcal{X}_2 - \frac{\psi-1}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_2)\phi\mathcal{X}_1 + \frac{\psi-1}{n-1}g(\mathcal{U}_1, \mathcal{X}_2)\eta(\mathcal{X}_1)\xi \\
& - \frac{\psi-1}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\eta(\mathcal{X}_2)\xi + \frac{n-\psi}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_1)\eta(\mathcal{X}_2)\xi - \frac{n-\psi}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_2)\eta(\mathcal{X}_1)\xi \\
& + \frac{n+\psi}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\mathcal{X}_2 - \frac{n+\psi}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_2)\mathcal{X}_1 + \frac{n+\psi}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\phi\mathcal{X}_2 \\
& - \frac{n+\psi}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_2)\phi\mathcal{X}_1 + \eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\phi^2\mathcal{U}_1 - \eta(\mathcal{X}_1)\eta(\mathcal{X}_2)\phi\mathcal{U}_1 \\
& - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\mathcal{U}_1 - \bar{R}(\mathcal{X}_1, \mathcal{X}_2)\phi\mathcal{U}_1 = 0.
\end{aligned} \tag{7.11}$$

Substituting $\mathcal{X}_2 = \xi$, and using (3.10) in (7.11), we find

$$\begin{aligned}
& \frac{1}{n-1}S(\mathcal{U}_1, \mathcal{X}_1)\xi + \frac{1}{n-1}S(\mathcal{U}_1, \phi\mathcal{X}_1)\xi + \frac{n+2\psi-3}{n-1}g(\mathcal{U}_1, \mathcal{X}_1)\xi \\
& + \frac{n+\psi-2}{n-1}g(\phi\mathcal{U}_1, \mathcal{X}_1)\xi + \frac{\psi-1}{n-1}g(\mathcal{U}_1, \phi\mathcal{X}_1)\xi + \frac{n+2\psi-1}{n-1}\eta(\mathcal{U}_1)\eta(\mathcal{X}_1)\xi \\
& - \eta(\mathcal{X}_1)\mathcal{U}_1 + \frac{2}{n-1}\eta(\mathcal{U}_1)\mathcal{X}_1 + \frac{2}{n-1}\eta(\mathcal{U}_1)\phi\mathcal{X}_1 + \eta(\mathcal{X}_1)\phi\mathcal{U}_1 = 0.
\end{aligned} \tag{7.12}$$

Taking inner product of (7.12) with ξ , we lead to

$$\begin{aligned}
S(\mathcal{U}_1, \mathcal{X}_1) + S(\mathcal{U}_1, \phi\mathcal{X}_1) &= -(n+2\psi-3)g(\mathcal{U}_1, \mathcal{X}_1) - (\psi-1)g(\mathcal{U}_1, \phi\mathcal{X}_1) \\
& - (n+\psi-2)g(\phi\mathcal{U}_1, \mathcal{X}_1) - 2(n+\psi-2)\eta(\mathcal{U}_1)\eta(\mathcal{X}_1).
\end{aligned} \tag{7.13}$$

Contracting above expression over \mathcal{U}_1 and \mathcal{X}_1 , we get

$$r = -[n^2 + (5\psi-1)n - (\psi+4)] - \text{tr}\phi Q. \tag{7.14}$$

The above relation leads to the following theorem:

Theorem 7.2. *The scalar curvature of an $(LPK)_n$ -manifold satisfying $\bar{W}_8 \cdot \bar{R} = 0$ is given by (7.14).*

Acknowledgement: The authors extend their appreciation to Umm Al-Qura University, Saudi Arabia for funding this research work through grant number: 25UQU4330007GSSR04.

Funding statement: This research work was funded by Umm Al-Qura University, Saudi Arabia under grant number: 25UQU4330007GSSR04.

Conflicts of Interest: The authors declare that there are no conflicts of interest regarding the publication of this paper.

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